



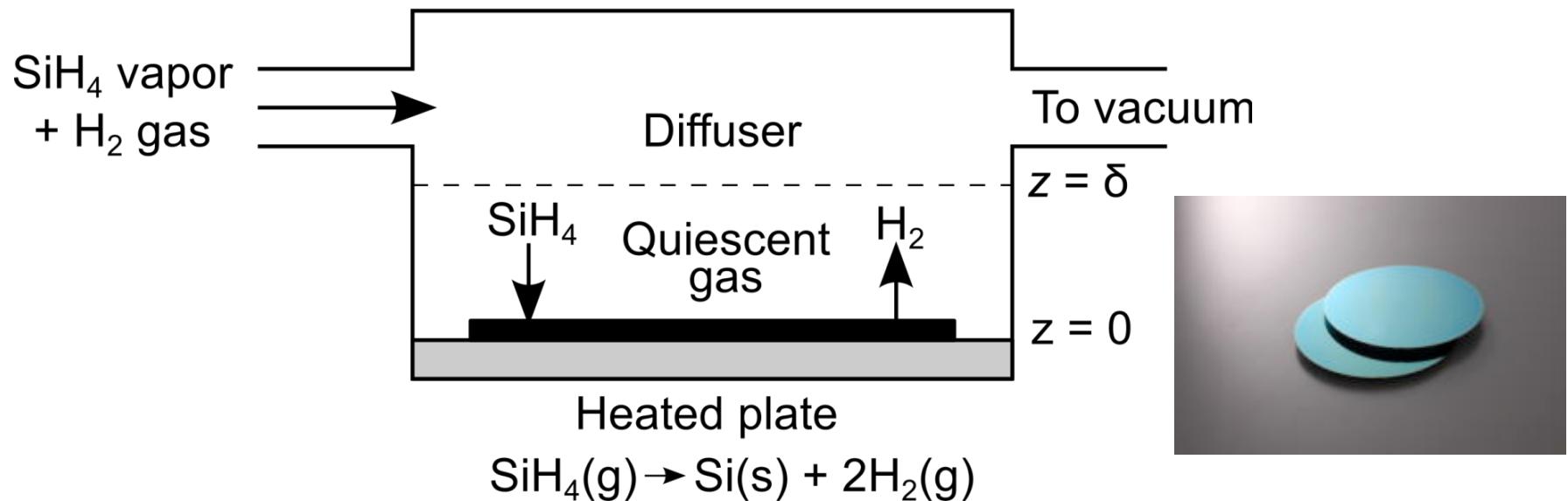
熱物質移動を含むプロセスへの オープンCAEの活用

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Chemical engineering process

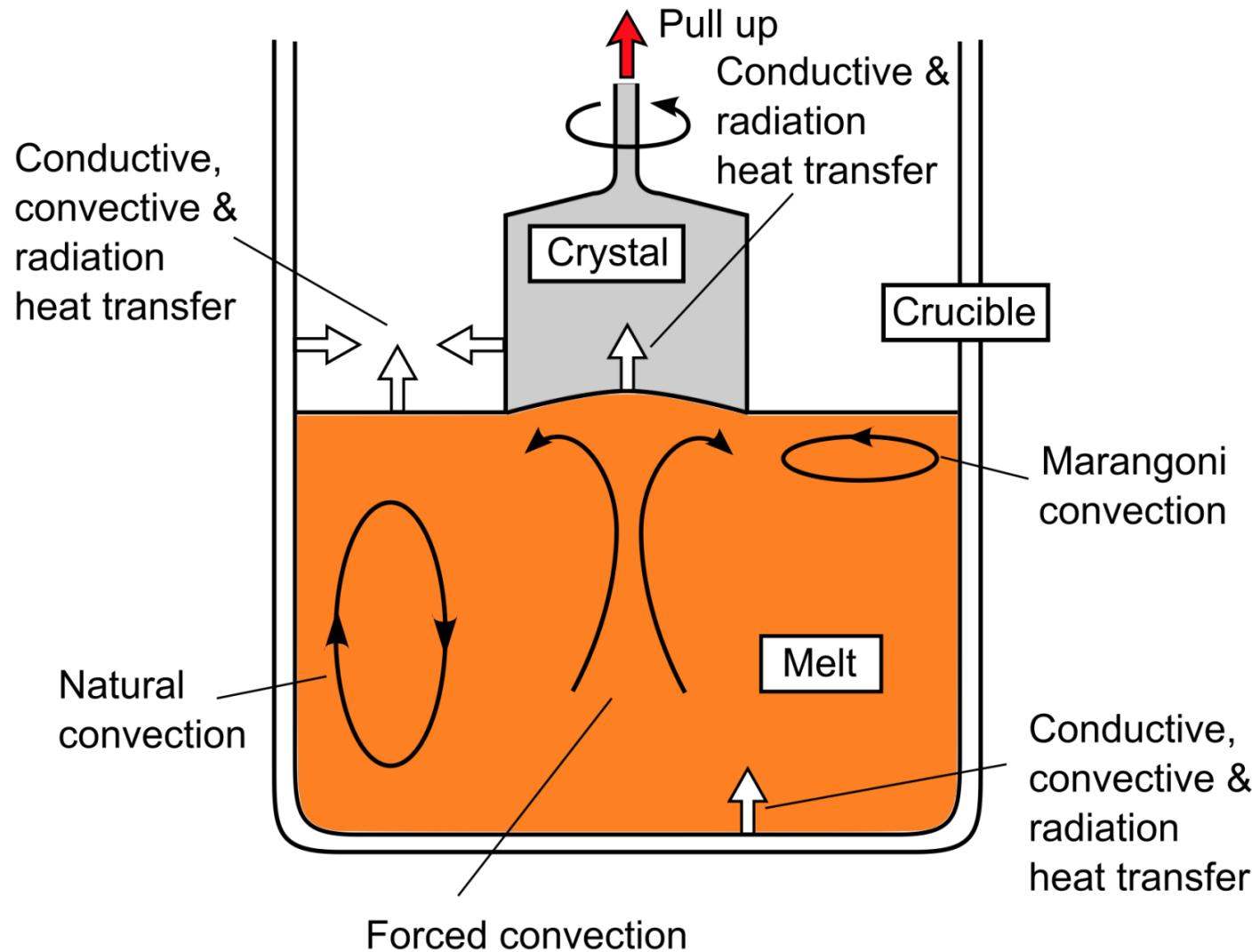
Ex. Chemical Vapor Deposition (CVD)



Heat, Mass and momentum transfer



Transport phenomena in melt





Governing equations in melt

- Navier-Stokes eq.

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho} \nabla P + \nu \nabla^2 \mathbf{u} + \mathbf{F}$$

- Energy eq.

$$\frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T = \alpha \nabla^2 T$$

- Diffusion eq.

$$\frac{\partial C}{\partial t} + \mathbf{u} \cdot \nabla C = D \nabla^2 C$$

\mathbf{u} : vector
 T : scalar
 C : scalar

Common operator:
Gradient, Divergence, Laplacian, Time Advancement



Advantage of open source

- OpenFOAM
 - Object Oriented Programming

```
grad(T)  
grad(U)
```

Operator overload
Class module



Easy extension

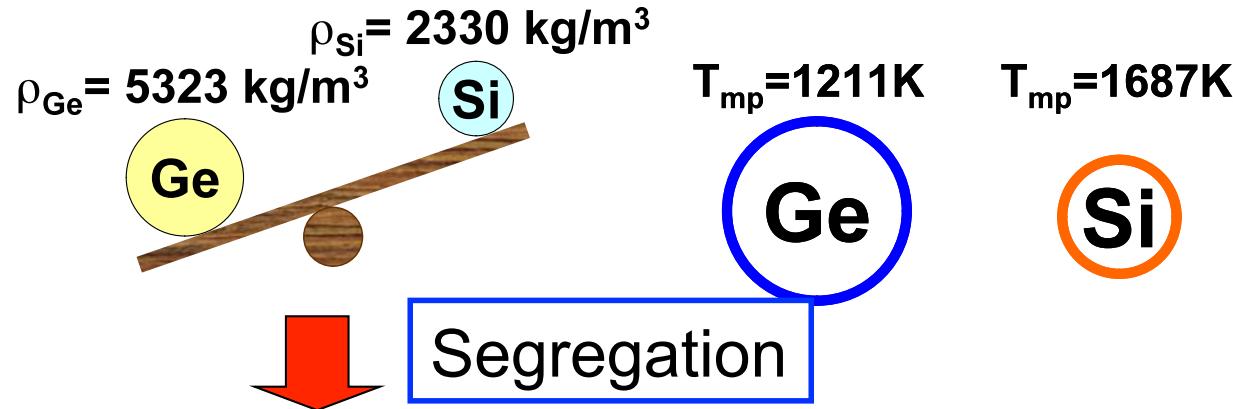
- Fortran code
 - Procedural Programming

```
call grad(T,dTdx,dTdy,dTdz)  
call grad(u,dudx,dudy,dudz)  
call grad(v,dvdx,dvdy,dvdz)  
call grad(w,dwdx,dwdv,dwdz)
```

Mixture of scalar, vector
and tensor

Crystal growth of compound semiconductor

- Silicon germanium (SiGe)
 - $(\text{Si}_x\text{Ge}_{1-x})$
 - High performance, high efficiency
 - Lattice mismatch in Si+SiGe
- Property of SiGe

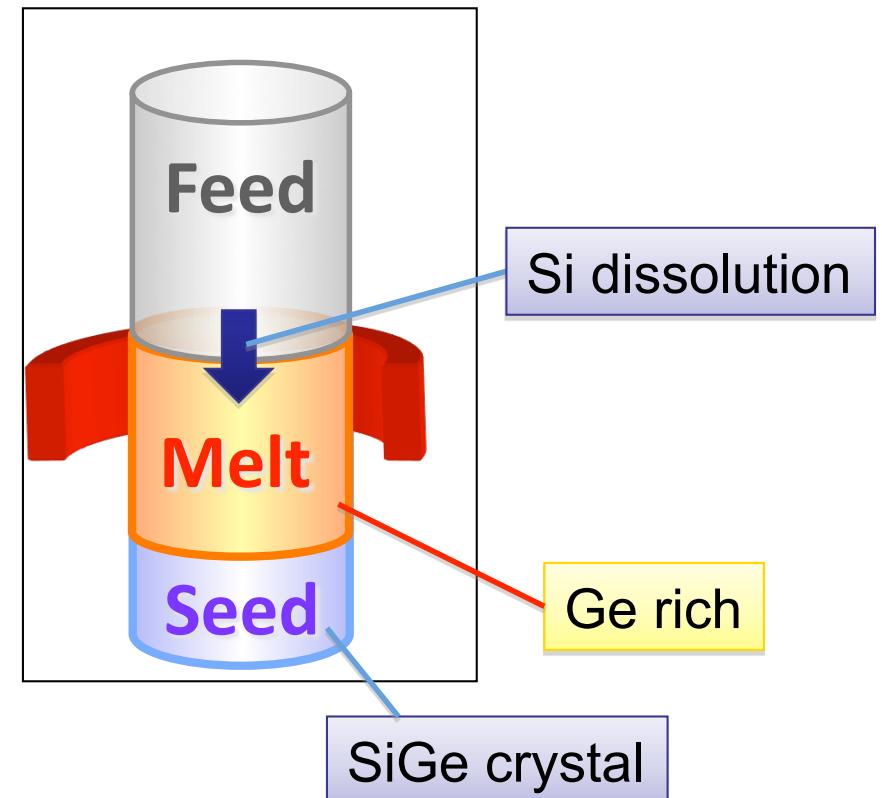
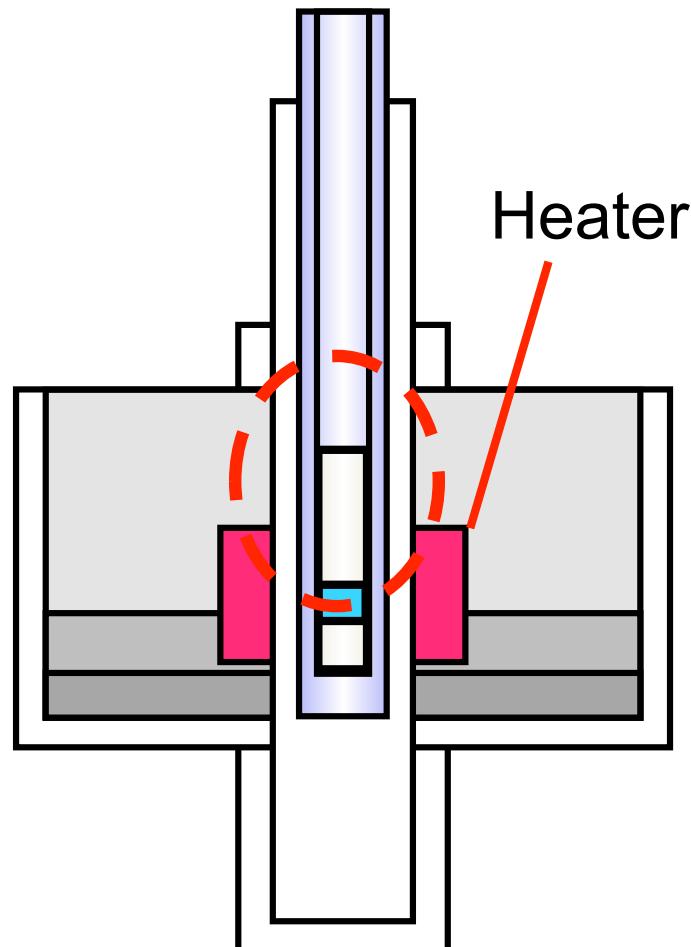


Use of solution growth





Traveling Heater Method (THM)

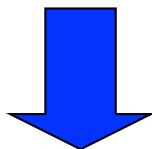


Melt convection with heat and mass transfers



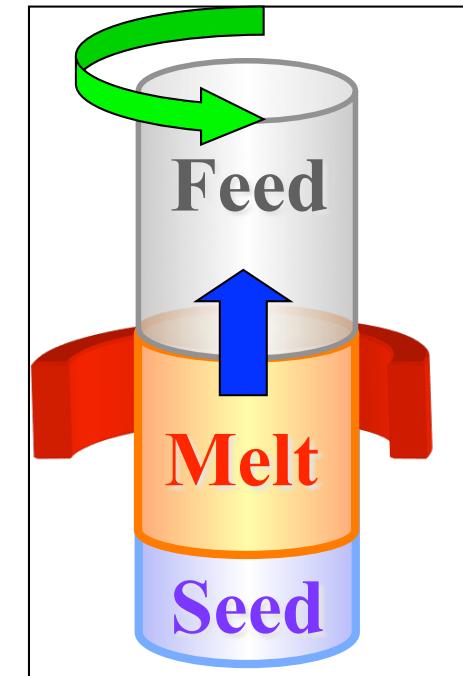
Objective

- Convection control in THM
 - Magnetic field
 - Crucible rotation



OpenFOAM

- Convection suppression effect with external forces
- Operating condition for high quality crystal
 - Si concentration near growth interface





Governing equations in melt

- Navier-Stokes eq.

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho} \nabla P + \nu \nabla^2 \mathbf{u} + \underline{\mathbf{S}} + \underline{\mathbf{F}}$$
$$\underline{\mathbf{S}} = (\beta_T g(T - T_0) - \beta_C g(C - C_0)) \mathbf{e}_z \quad \underline{\mathbf{F}} = \mathbf{J} \times \mathbf{B}$$

- Induction eq. of magnetic field

$$\frac{\partial \mathbf{B}}{\partial t} + \nabla \cdot (\mathbf{u} \times \mathbf{B} - \mathbf{B} \times \mathbf{u}) - \nabla \cdot \frac{1}{\sigma\mu} \nabla \mathbf{B} = 0$$

- Energy eq.

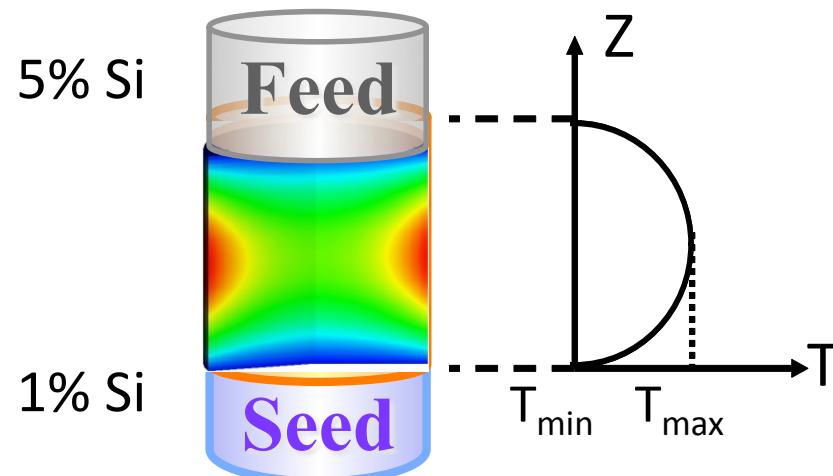
$$\frac{\partial T}{\partial t} + \mathbf{u} \cdot \nabla T = \alpha \nabla^2 T$$

- Diffusion eq.

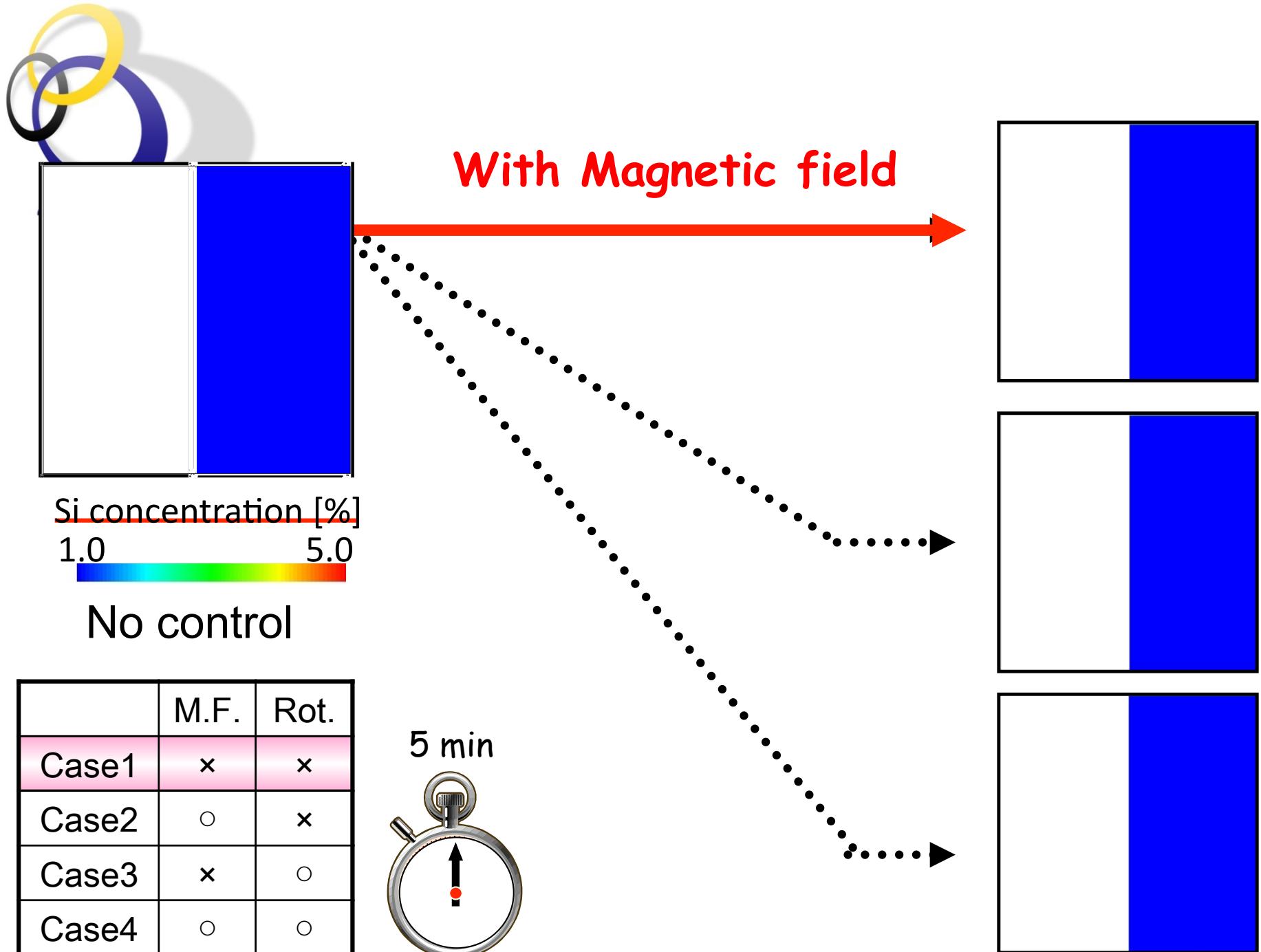
$$\frac{\partial C}{\partial t} + \mathbf{u} \cdot \nabla C = D \nabla^2 C$$

Boundary condition

- Velocity: no-slip condition, rotating wall velocity
- Magnetic field : static vertical
- Temperature and concentration:



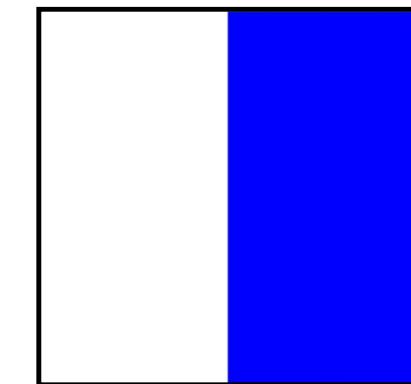
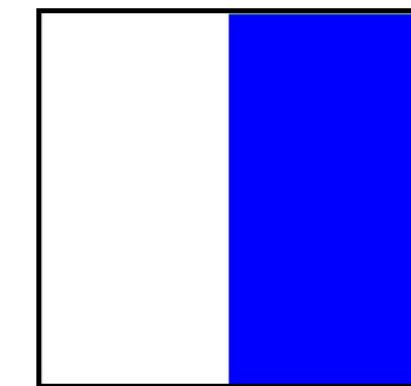
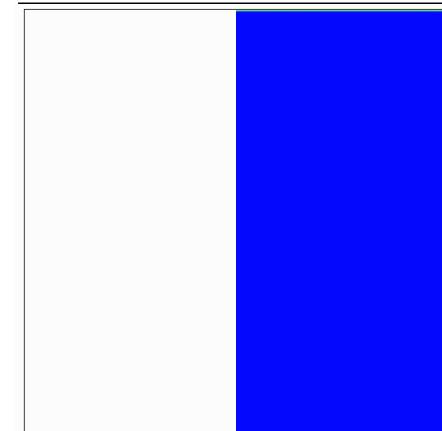
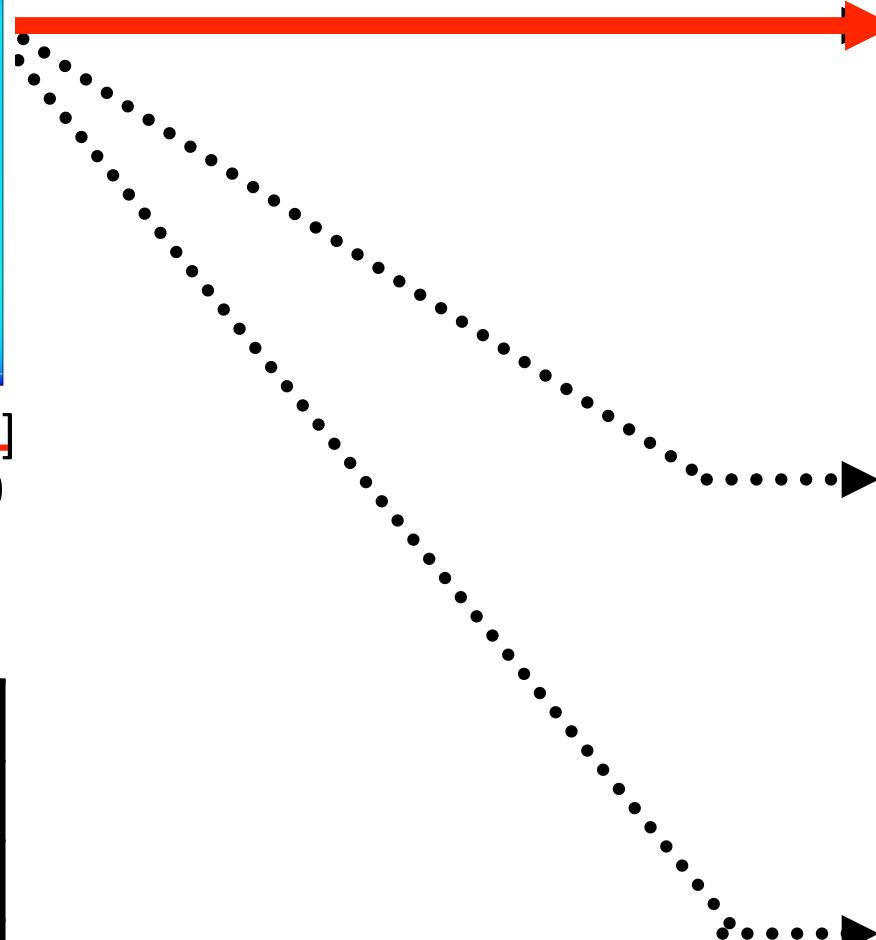
- Not considered: moving boundary of crystal-melt surface, heater movement



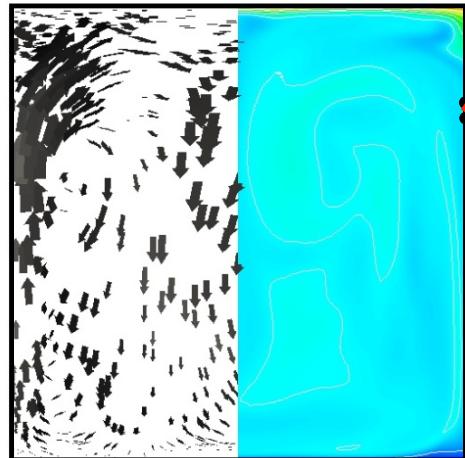


No control

With Magnetic field



	M.F.	Rot.
Case1	×	×
Case2	○	×
Case3	×	○
Case4	○	○

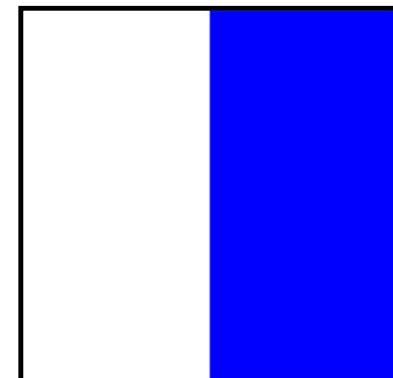
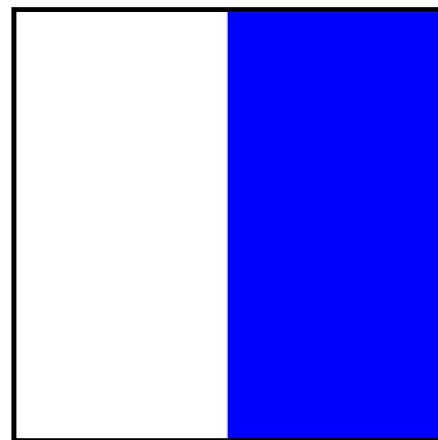
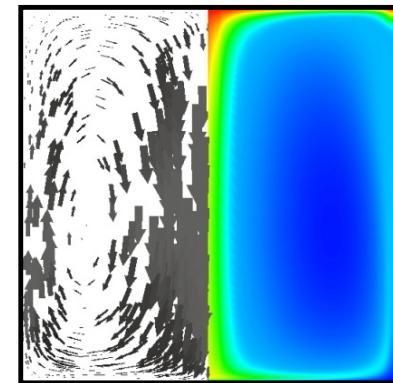


Si concentration [%]
1.0 5.0

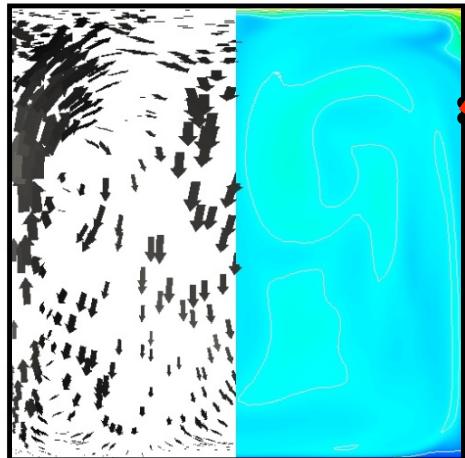
With Magnetic field

$V_{max}=1.04 \text{ m/s}$
 $V_z max=0.07 \text{ m/s}$

With rotation



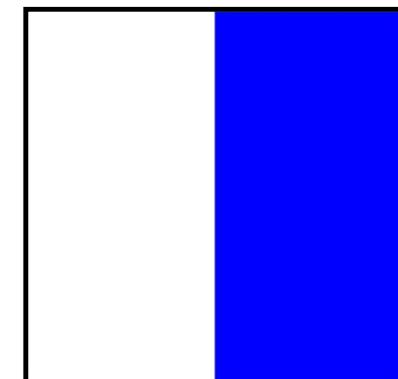
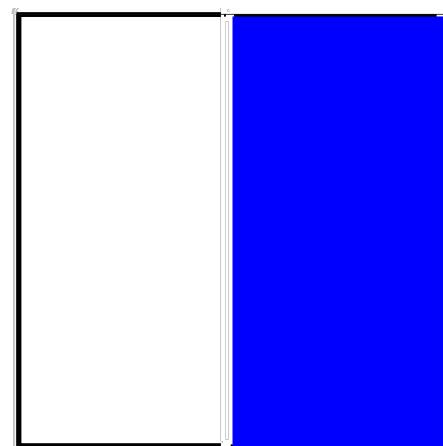
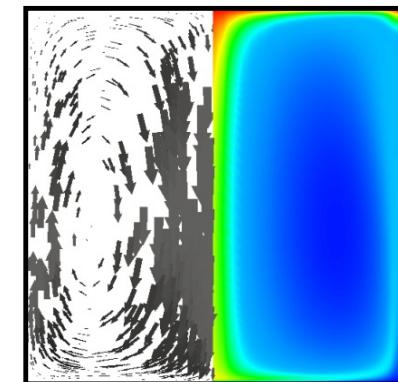
	M.F.	Rot.
Case1	×	×
Case2	○	×
Case3	×	○
Case4	○	○



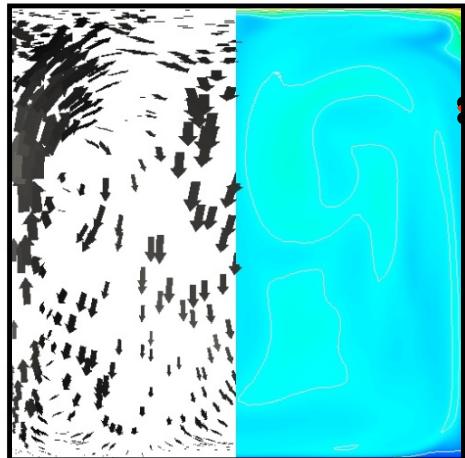
With Magnetic field

$V_{\max} = 1.04 \text{ m/s}$
 $V_z \max = 0.07 \text{ m/s}$

With rotation

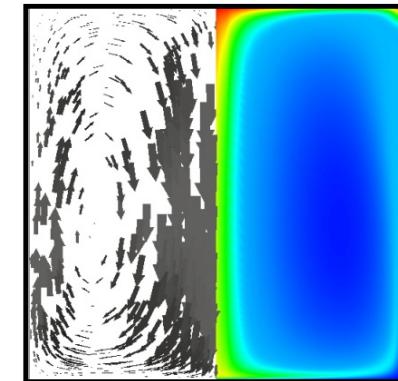


	M.F.	Rot.
Case1	×	×
Case2	○	×
Case3	×	○
Case4	○	○

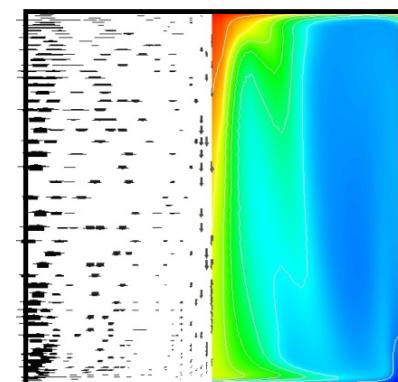


Si concentration [%]
1.0 5.0

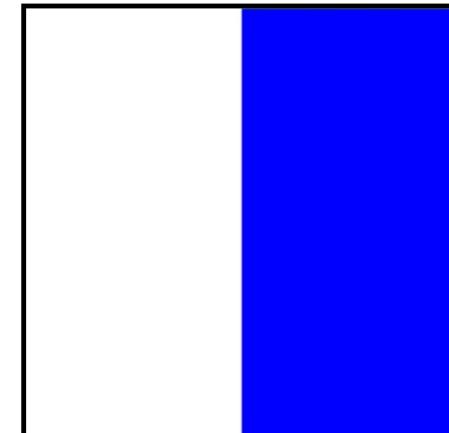
With Magnetic field



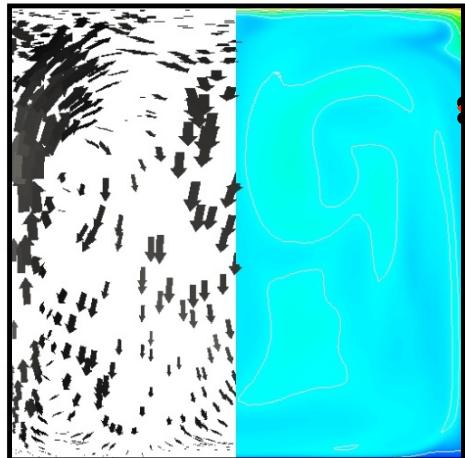
With rotation



With rotation
& Magnetic field



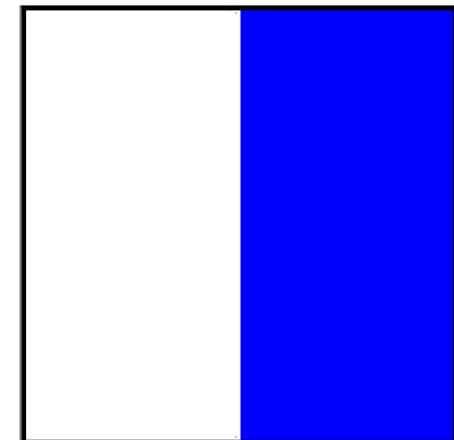
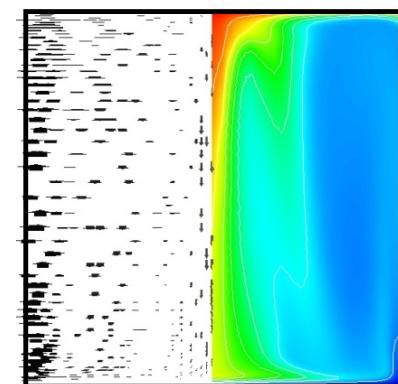
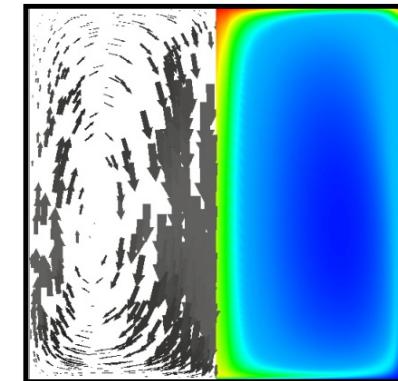
	M.F.	Rot.
Case1	×	×
Case2	○	×
Case3	×	○
Case4	○	○

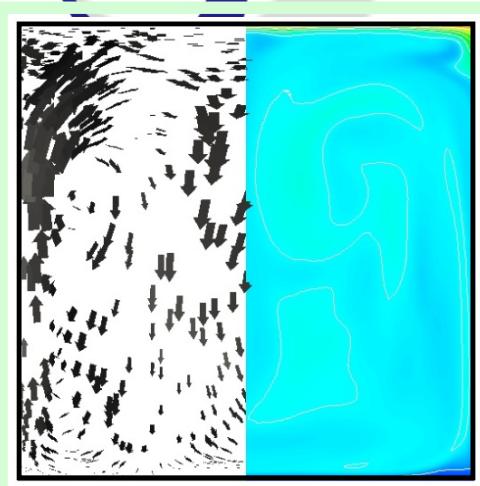


Si concentration [%]
1.0 5.0

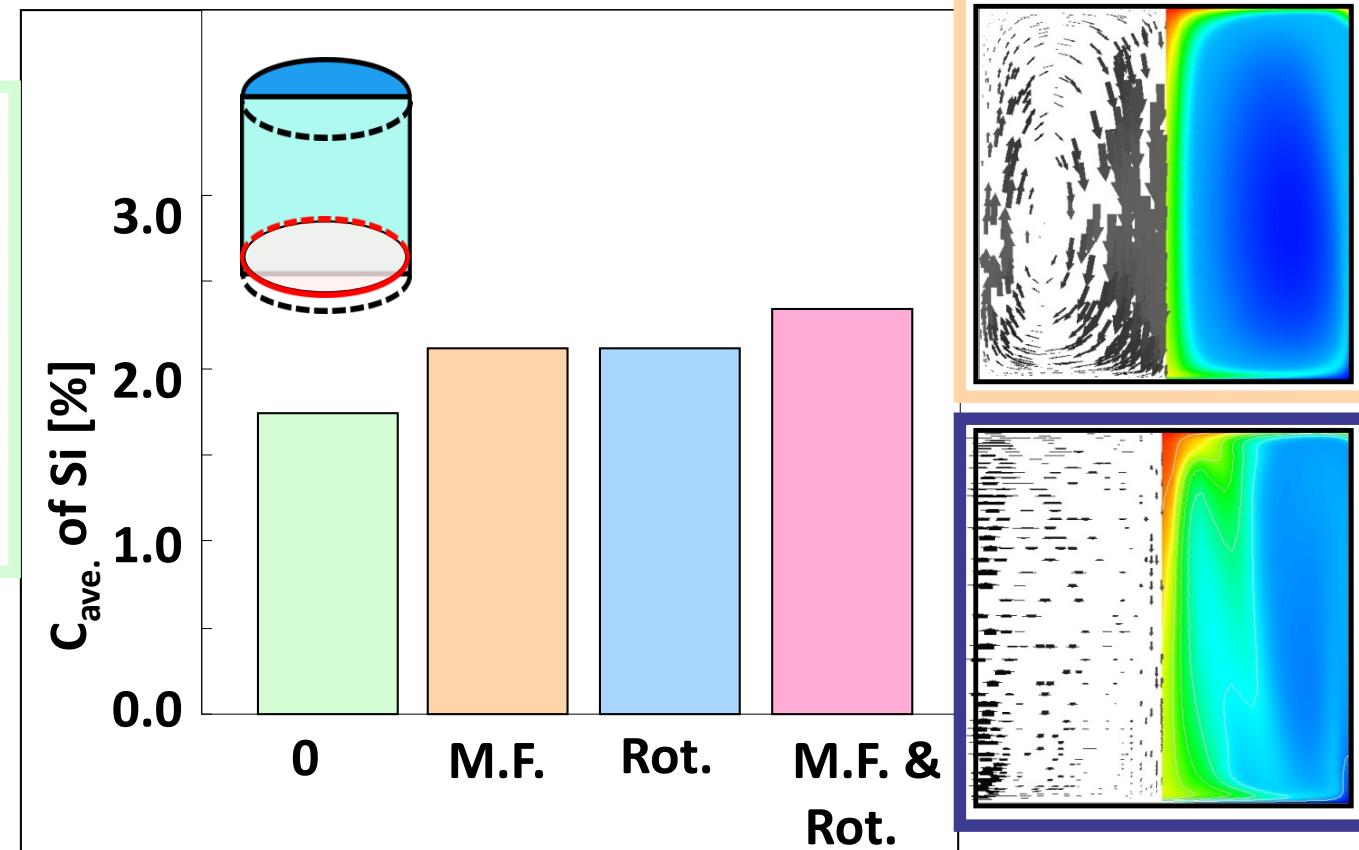
	M.F.	Rot.
Case1	×	×
Case2	○	×
Case3	×	○
Case4	○	○

With rotation
& Magnetic field





Si concentration [%]
1.0 5.0



	M.F.	Rot.
--	------	------



Case

Case

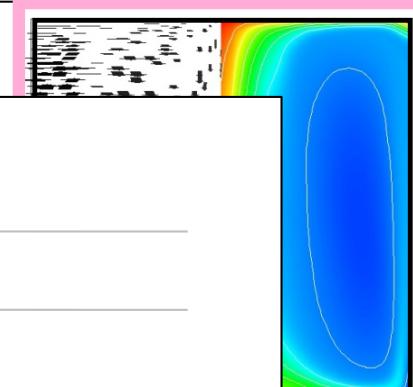
Case

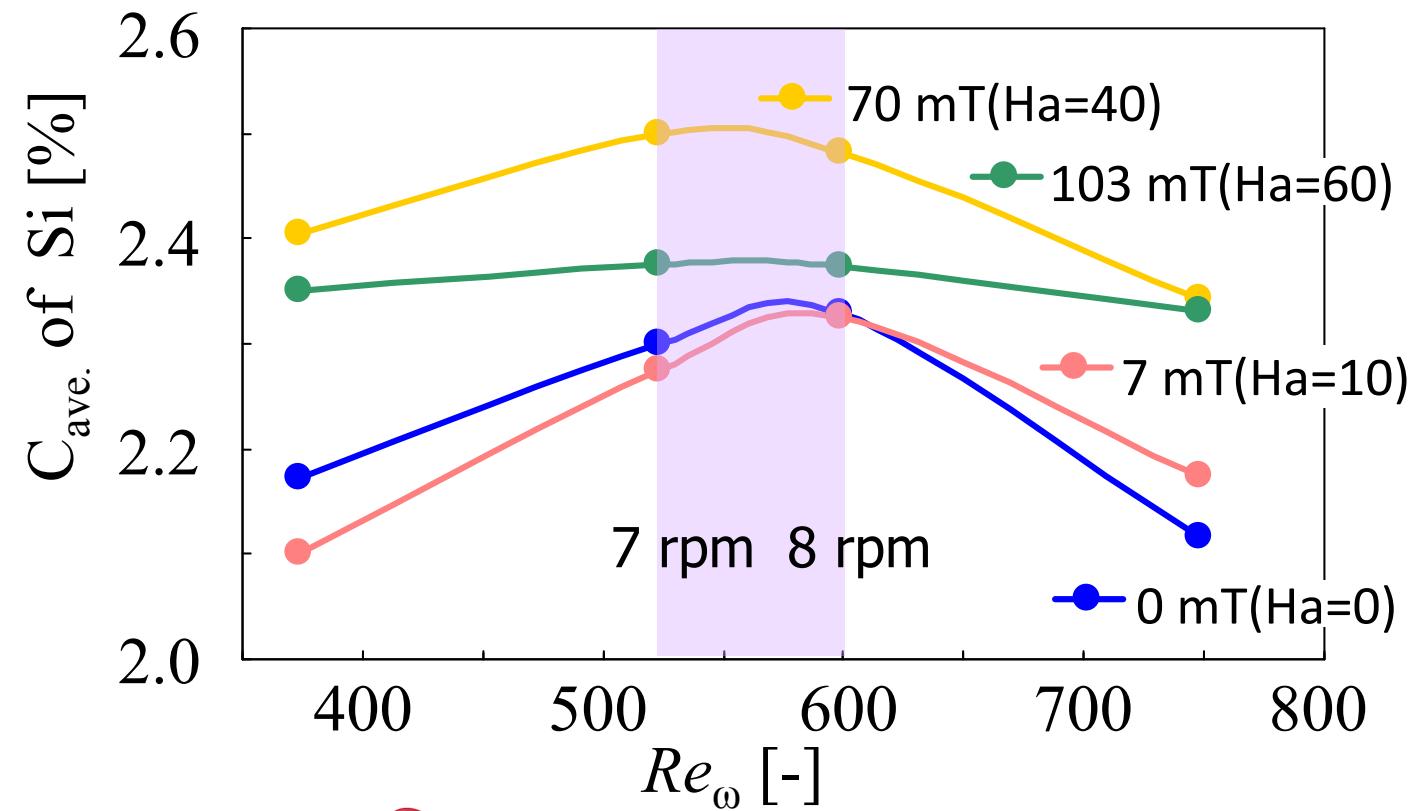
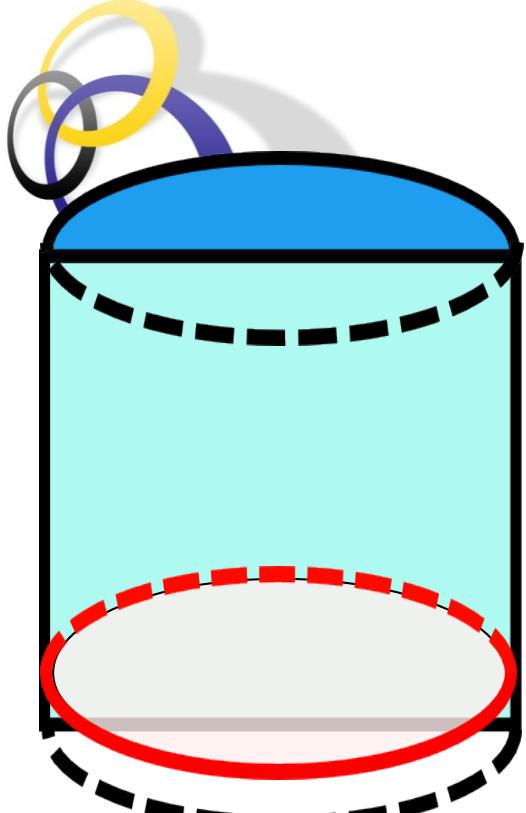
Case

★ *Combination of M.F. and rotation*



Rich Si near growth interface





★ Combination of M.F. and rotation
7-8 rpm & around 70mT(Ha=40)

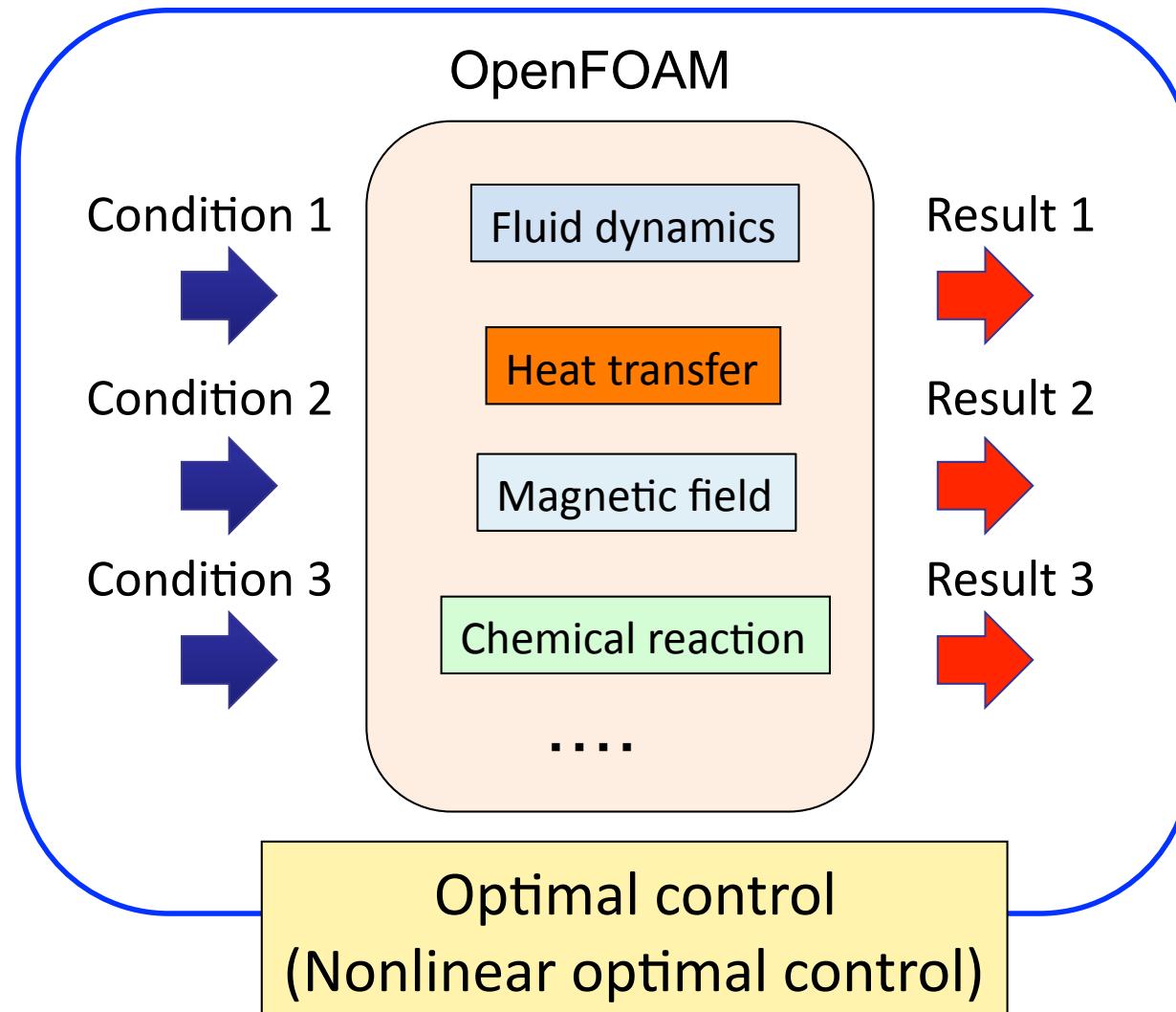
Rich Si near growth interface



Best



Toward smart control





First step for smart control: Adjoint method

Adjoint method formulation for ducted flow

- Adjoint N-S equations:

$$-2D(\mathbf{u})\mathbf{v} = -\nabla q + \nabla \cdot (2\nu D(\mathbf{u})) - \alpha \mathbf{u}$$

$$\nabla \cdot \mathbf{u} = 0$$

- Adjoint BCs for the wall and inlet:

$$\mathbf{u}_t = 0, \quad u_n = -\frac{\partial J_\Gamma}{\partial p}$$

$$\mathbf{n} \cdot \nabla q = 0$$

- Adjoint BCs for the outlet:

$$q = \mathbf{u} \cdot \mathbf{v} + u_n v_n + \nu (\mathbf{n} \cdot \nabla) u_n + \frac{\partial J_\Gamma}{\partial v_n}$$

$$0 = v_n \mathbf{u}_t + \nu (\mathbf{n} \cdot \nabla) \mathbf{u}_t + \frac{\partial J_\Gamma}{\partial \mathbf{v}_t}$$



Ex. 1: Dissipated power

Cost function:

$$J := - \int_{\Gamma} d\Gamma \left(p + \frac{1}{2} v^2 \right) \mathbf{v} \cdot \mathbf{n}$$

$$J_{\Omega} = 0, \quad J_{\Gamma} = - \left(p + \frac{1}{2} v^2 \right) \mathbf{v} \cdot \mathbf{n}$$

Derivatives for BCs:

$$\frac{\partial J_{\Gamma}}{\partial p} = -\mathbf{v} \cdot \mathbf{n},$$

$$\frac{\partial J_{\Gamma}}{\partial \mathbf{v}} = - \left(p + \frac{1}{2} v^2 \right) \mathbf{n} - (\mathbf{v} \cdot \mathbf{n}) \mathbf{v}$$

Adjoint BCs for the wall and inlet:

$$\mathbf{u}_t = 0 \quad \text{at wall}$$

$$u_n = \begin{cases} 0 & \text{at inlet} \\ v_n & \end{cases}$$

Adjoint BCs for the outlet:

$$q = \mathbf{u} \cdot \mathbf{v} + u_n v_n + \nu(\mathbf{n} \cdot \nabla) u_n - \frac{1}{2} v^2 - v_n^2$$

$$0 = v_n (\mathbf{u}_t - \mathbf{v}_t) + \nu(\mathbf{n} \cdot \nabla) \mathbf{u}_t$$



adjointShapeOptimization.C

```
// Adjoint Pressure-velocity SIMPLE corrector
{
    // Adjoint Momentum predictor

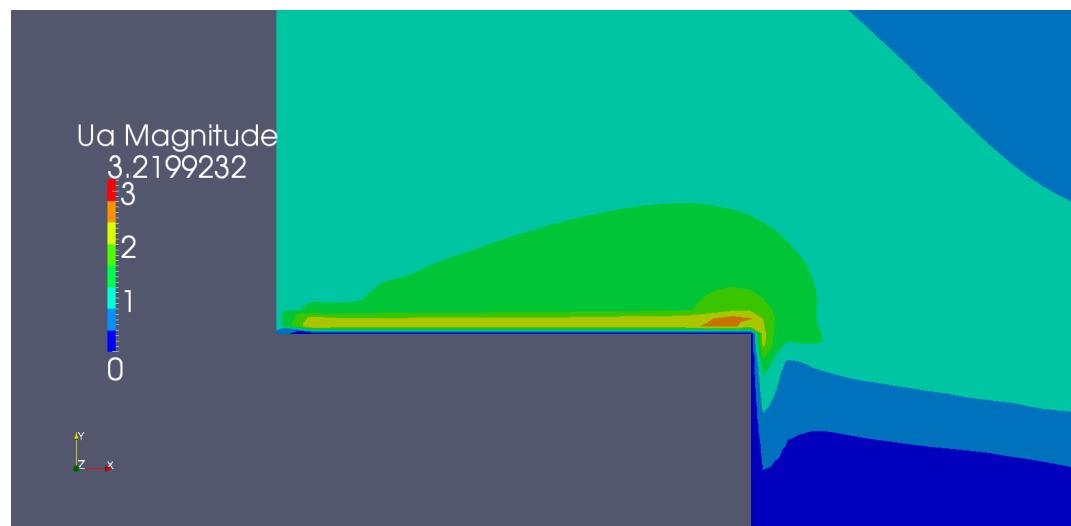
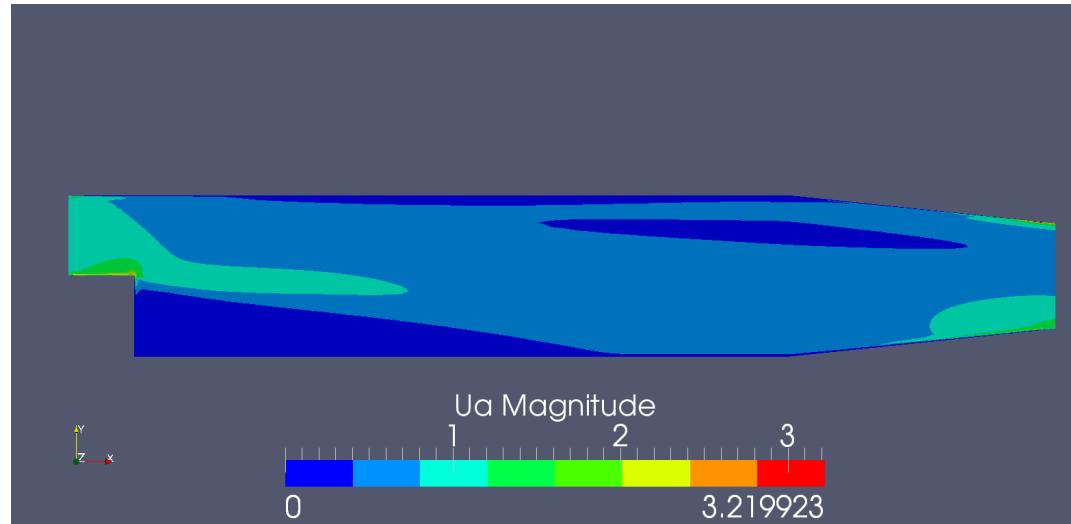
    volVectorField adjointTransposeConvection((fvc::grad( $\nabla a$ ) &
U));

    zeroCells(adjointTransposeConvection, inletCells);

    tmp<fvVectorMatrix> UaEqn
    (
        fvm::div(-phi, Ua)                                $\nabla \cdot (-\phi \mathbf{u})$ 
        - adjointTransposeConvection                     $-\nabla \mathbf{u} \cdot \mathbf{v}$ 
        + turbulence->divDevReff(Ua)                   $-\nabla \cdot (2\nu D(\mathbf{u}))$ 
        + fvm::Sp(alpha, Ua)                            $+\alpha \mathbf{u}$ 
    );
}
```



Result: adjoint velocity





Summary

- The simulation including heat, mass and momentum transfers is carried out by using OpenFOAM.
- OpenFOAM is suitable for multi-physics problem.
- Simulation code for optimization is now developed.